

H4 (left) and H4Φ (right) 24-Cell

The left images are scaled up to the same size as the right image in order to show more detail.

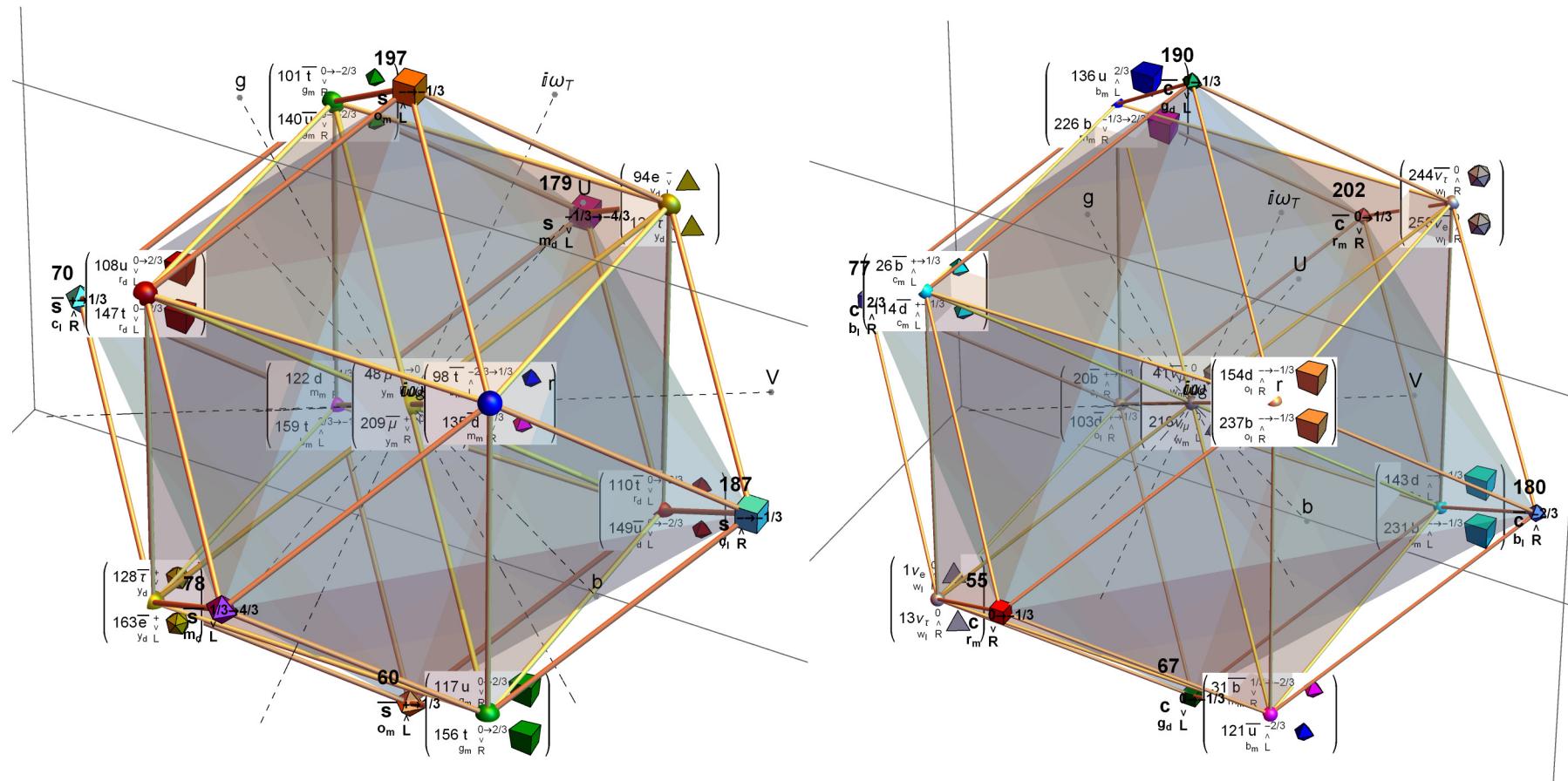
This accounts for the thicker edges and larger vertex shapes in the left image.

The light blue octahedron is the 8 vertex 16-cell.

The light red cube is the 16 vertex 8-cell (a Tesseract) with dual vertices at each corner.

In these 3D projections of hyper-dimensional objects, we do not scale the 4th dimension as is sometime shown for the Tesseract.

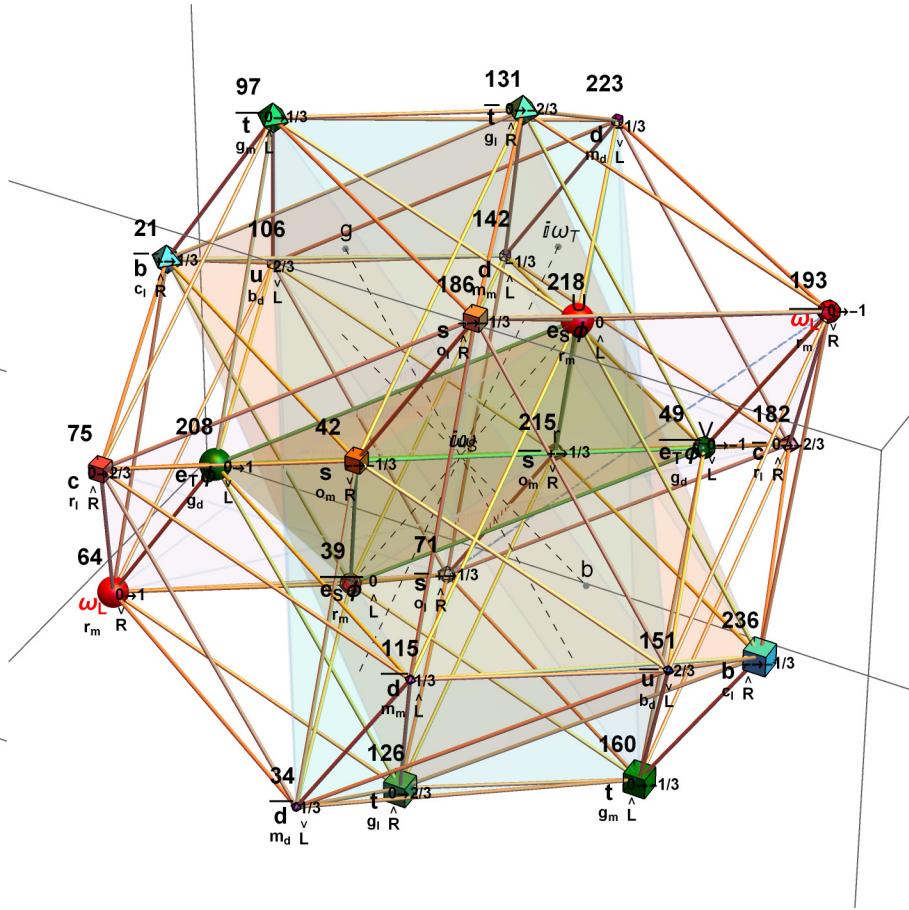
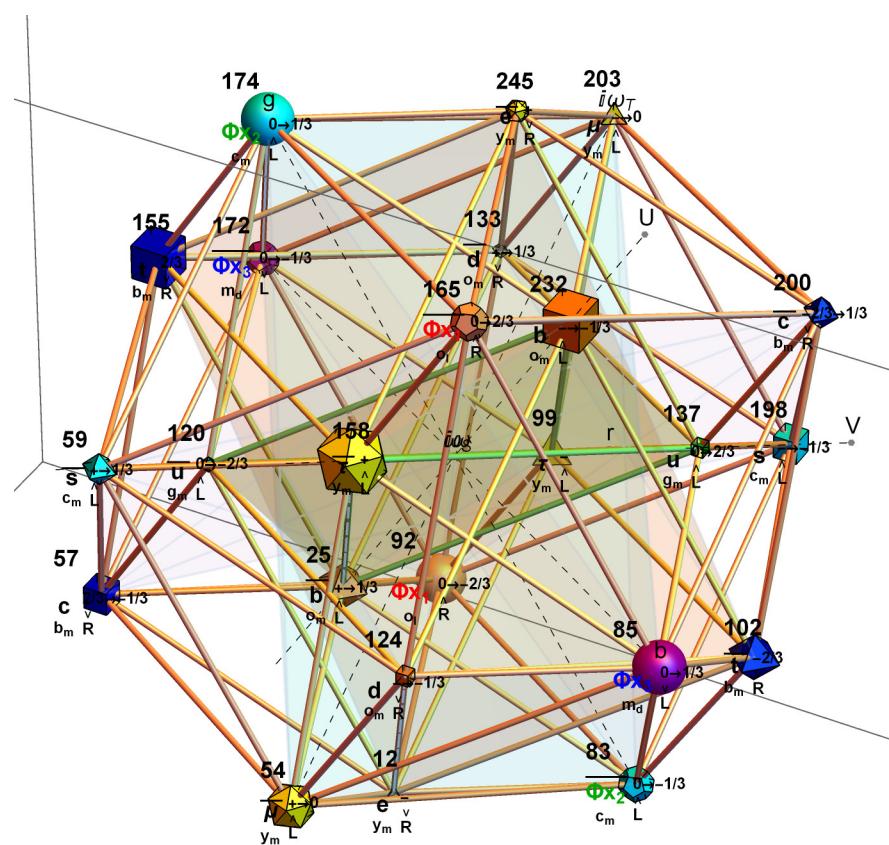
All objects (above and below) use the same projection basis vectors. The only difference is in the selection from the 240 8D E8 vertices being projected.



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ColumnForm[MatrixForm[{Row@{Column[{n, pDisp@#, pBl@#, Center}] & /@ n}] & /@ {h4cell16, h4cell18, h4cell16, h4cell18}]
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48	60	70	78	179	187	197	209	
$\mu \stackrel{-0}{\nu}$ $y_m R$	$\overline{s} \stackrel{+0}{\wedge}$ $\overline{o}_m L$	$\overline{s} \stackrel{+0}{\wedge}$ $c_l R$	$\overline{s} \stackrel{1/3 \rightarrow 1/3}{\wedge}$ $m_d L$	$s \stackrel{1/3 \rightarrow 4/3}{\wedge}$ $m_d L$	$s \stackrel{-1/3 \rightarrow -4/3}{\wedge}$ $c_l R$	$s \stackrel{-0}{\wedge}$ $y_m L$	$\overline{\mu} \stackrel{+0}{\nu}$ $y_m R$	
94	98	101	108	110	117	122	128	129
$e \stackrel{-}{\nu}$ $y_d L$	$\overline{t} \stackrel{-2/3 \rightarrow 1/3}{\wedge}$ $b_m L$	$\overline{t} \stackrel{0 \rightarrow -2/3}{\wedge}$ $g_m R$	$u \stackrel{0 \rightarrow 2/3}{\wedge}$ $r_d L$	$\overline{t} \stackrel{0 \rightarrow -2/3}{\wedge}$ $r_d L$	$u \stackrel{0 \rightarrow 2/3}{\wedge}$ $g_m R$	$d \stackrel{-1/3}{\wedge}$ $m_m R$	$\overline{\tau} \stackrel{+}{\nu}$ $y_d L$	$\tau \stackrel{-}{\nu}$ $y_d L$
41	55	67	77	180	190	202	216	
$\overline{\nu_\mu} \stackrel{0}{\wedge}$ $w_m L$	$c \stackrel{0 \rightarrow -1/3}{\wedge}$ $r_m R$	$c \stackrel{0 \rightarrow -1/3}{\wedge}$ $g_d L$	$c \stackrel{2/3}{\wedge}$ $b_l R$	$\overline{c} \stackrel{-2/3}{\wedge}$ $b_l R$	$\overline{c} \stackrel{0 \rightarrow 1/3}{\wedge}$ $g_d L$	$\overline{c} \stackrel{0 \rightarrow 1/3}{\wedge}$ $r_m R$	$\nu_\mu \stackrel{0}{\wedge}$ $w_m L$	
1	13	20	26	31	103	114	121	136
$\nu_e \stackrel{0}{\wedge}$ $w_l R$	$\nu_\tau \stackrel{0}{\wedge}$ $w_l R$	$\overline{b} \stackrel{+0}{\wedge}$ $o_l R$	$\overline{b} \stackrel{+0}{\wedge}$ $c_m L$	$\overline{b} \stackrel{1/3 \rightarrow -2/3}{\wedge}$ $m_m R$	$\overline{d} \stackrel{+0}{\wedge}$ $o_l R$	$\overline{d} \stackrel{+0}{\wedge}$ $c_m L$	$\overline{u} \stackrel{-2/3}{\wedge}$ $b_m L$	$u \stackrel{2/3}{\wedge}$ $b_m L$
							$d \stackrel{-0}{\wedge}$ $c_m L$	$d \stackrel{-0}{\wedge}$ $o_l R$
							$b \stackrel{-1/3 \rightarrow 2/3}{\wedge}$ $m_m R$	$b \stackrel{-0}{\wedge}$ $c_m L$
							$b \stackrel{-0}{\wedge}$ $o_l R$	$\overline{\nu_\tau} \stackrel{0}{\wedge}$ $w_l R$
								$\overline{\nu_e} \stackrel{0}{\wedge}$ $w_l R$

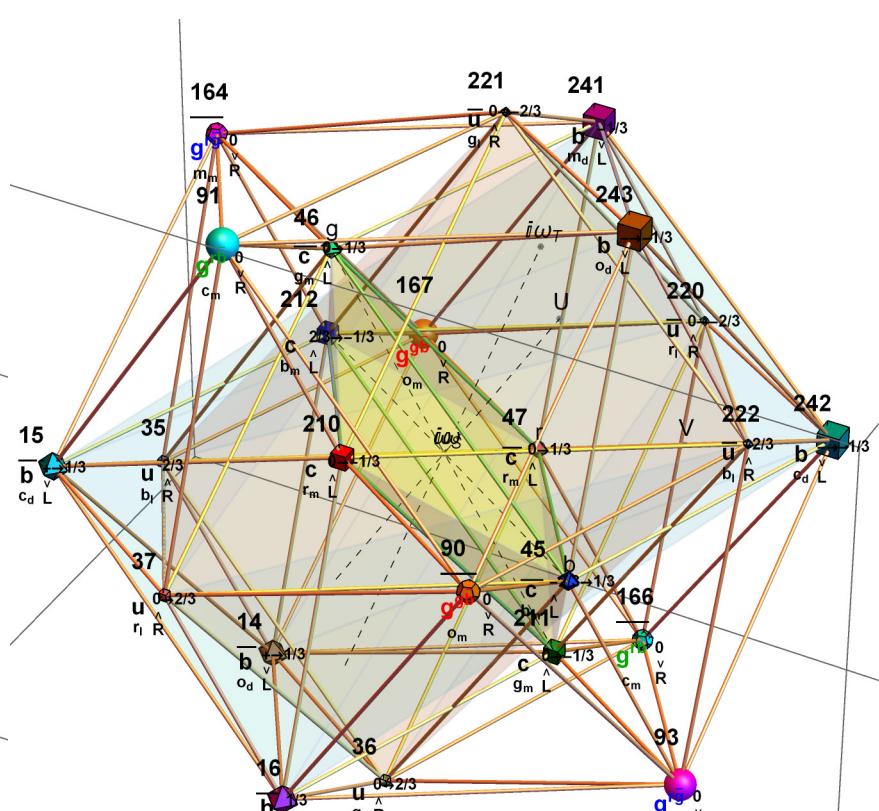
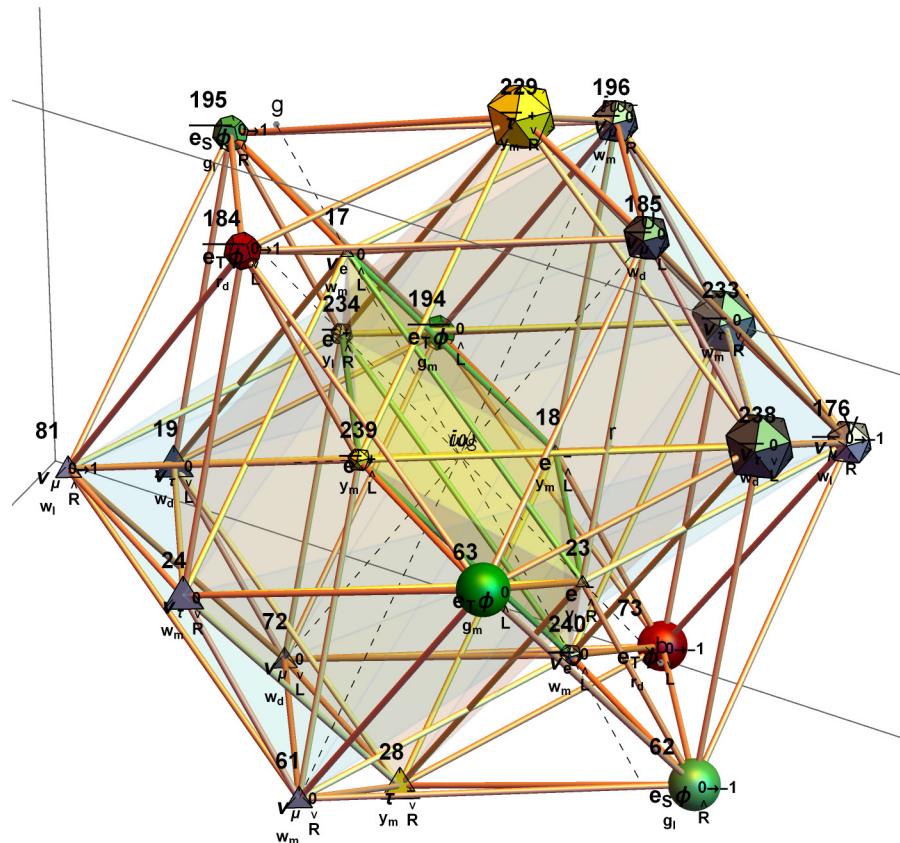
H4 (left) and H4Φ (right) Snub 24-Cell (1st of 4 rotations by  $\frac{\pi}{5}$  from the 0th rotation shown above)



```
ColumnForm[MatrixForm[{Row@{Column[{#, pDisp@#, pLble@#}, Center]} & /@ #]} & /@ {h4snub161, h4snub81, h4&snub161, h4&snub81}]
```

137	92	155	54	203	102	165	120	
								
$u \overset{0 \rightarrow 2/3}{\underset{g_m L}{\wedge}}$	$\Phi x_1 \overset{0 \rightarrow -2/3}{\underset{o_l R}{\wedge}}$	$t \overset{2/3}{\underset{b_m R}{\vee}}$	$\bar{\mu} \overset{+ \rightarrow 0}{\underset{y_m L}{\wedge}}$	$\mu \overset{- \rightarrow 0}{\underset{y_m L}{\wedge}}$	$\bar{t} \overset{-2/3}{\underset{b_m R}{\vee}}$	$\Phi \bar{x}_1 \overset{0 \rightarrow 2/3}{\underset{o_l R}{\wedge}}$	$\bar{u} \overset{0 \rightarrow -2/3}{\underset{g_m L}{\wedge}}$	
232	124	174	59	99	12	172	57	200
								
$b \overset{- \rightarrow -1/3}{\underset{o_m L}{\wedge}}$	$d \overset{- \rightarrow -1/3}{\underset{o_m R}{\vee}}$	$\Phi x_2 \overset{0 \rightarrow 1/3}{\underset{c_m L}{\wedge}}$	$\bar{s} \overset{+ \rightarrow 1/3}{\underset{c_m L}{\wedge}}$	$\tau \overset{-}{\underset{y_m L}{\wedge}}$	$e \overset{-}{\underset{y_m R}{\wedge}}$	$\Phi \bar{x}_3 \overset{0 \rightarrow -1/3}{\underset{m_d L}{\vee}}$	$c \overset{2/3 \rightarrow -1/3}{\underset{b_m R}{\vee}}$	$\bar{c} \overset{-2/3 \rightarrow 1/3}{\underset{b_m R}{\vee}}$
49	34	71	21	236	186	223	208	
								
$\bar{e}_T \phi \overset{0 \rightarrow -1}{\underset{g_d L}{\vee}}$	$\bar{d} \overset{1/3}{\underset{m_d L}{\vee}}$	$\bar{s} \overset{+ \rightarrow 1/3}{\underset{o_l R}{\wedge}}$	$\bar{b} \overset{+ \rightarrow 1/3}{\underset{c_l R}{\wedge}}$	$b \overset{- \rightarrow -1/3}{\underset{c_l R}{\wedge}}$	$s \overset{- \rightarrow -1/3}{\underset{o_l R}{\wedge}}$	$d \overset{-1/3}{\underset{m_d L}{\vee}}$	$e_T \phi \overset{0 \rightarrow 1}{\underset{g_d L}{\vee}}$	
39	64	142	42	160	106	75	126	131
								
$\bar{e}_S \phi \overset{0 \wedge}{\underset{r_m L}{\wedge}}$	$\omega_L \overset{0 \rightarrow 1}{\underset{r_m R}{\vee}}$	$d \overset{-1/3}{\underset{m_m L}{\wedge}}$	$s \overset{- \rightarrow -1/3}{\underset{o_m R}{\wedge}}$	$t \overset{0 \rightarrow -1/3}{\underset{g_m L}{\wedge}}$	$u \overset{2/3}{\underset{b_d L}{\vee}}$	$c \overset{0 \rightarrow 2/3}{\underset{r_i R}{\wedge}}$	$t \overset{0 \rightarrow 2/3}{\underset{g_i R}{\wedge}}$	$\bar{t} \overset{0 \rightarrow -2/3}{\underset{r_i R}{\wedge}}$
								$\bar{c} \overset{0 \rightarrow -2/3}{\underset{r_i R}{\wedge}}$
								$\bar{u} \overset{-2/3}{\underset{b_d L}{\wedge}}$
								$\bar{t} \overset{0 \rightarrow 1/3}{\underset{g_m L}{\wedge}}$
								$\bar{s} \overset{+ \rightarrow 1/3}{\underset{o_m R}{\wedge}}$
								$\bar{d} \overset{1/3}{\underset{m_m L}{\wedge}}$
								$\omega_L \overset{0 \rightarrow -1}{\underset{r_m R}{\vee}}$
								$e_S \phi \overset{0 \wedge}{\underset{r_m L}{\wedge}}$

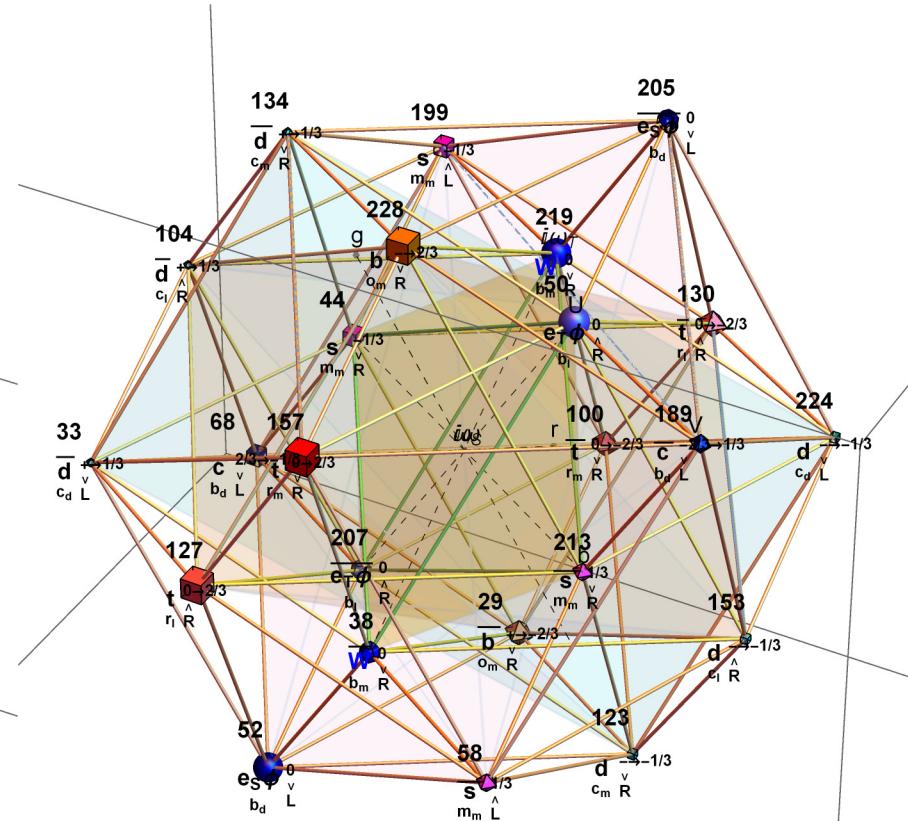
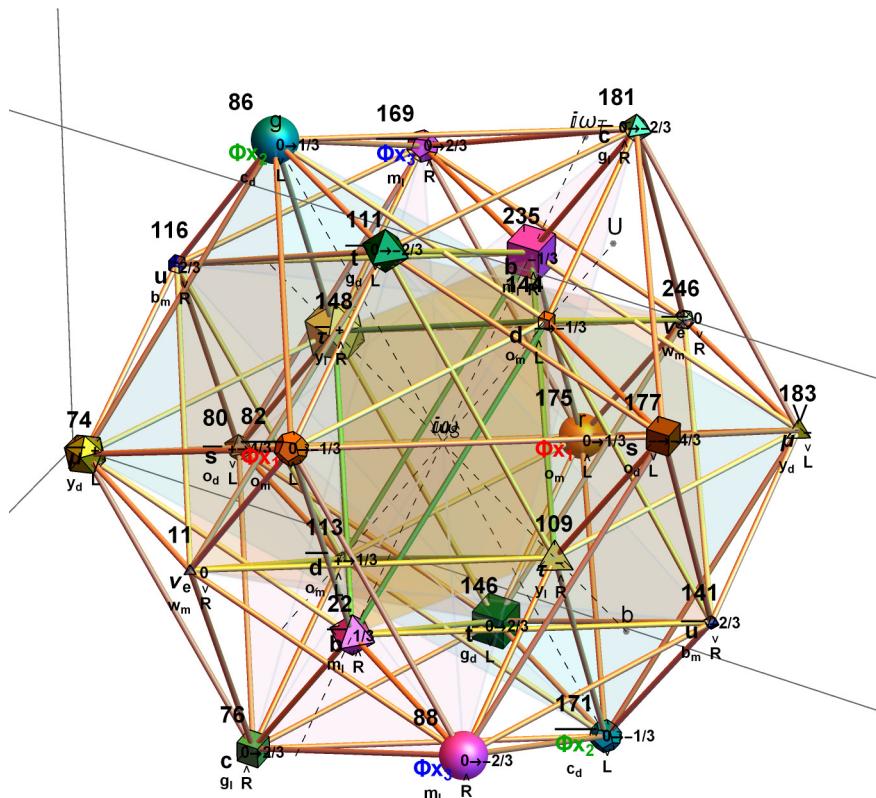
H4 (left) and H4Φ (right) Snub 24-Cell (2nd of 4 rotations by  $\frac{\pi}{5}$ )



```
ColumnForm[MatrixForm[Row@{Column[{#, p0Disp@#, p1Disp@#, Center}] & /@ #}]] & /@ {h4snub162, h4snub82, h4&snub162, h4&snub82}]
```

176	194	17	28	229	240	63	81	
$\overline{\nu_\mu} \stackrel{0}{\wedge} \stackrel{1}{R}$	$\overline{e_T \phi} \stackrel{0}{\wedge} \stackrel{1}{L}$	$\nu_e \stackrel{0}{\wedge} \stackrel{1}{L}$	$\tau \stackrel{-}{\vee} \stackrel{1}{R}$	$\overline{\tau} \stackrel{+}{\vee} \stackrel{1}{R}$	$\overline{\nu_e} \stackrel{0}{\wedge} \stackrel{1}{L}$	$e_T \phi \stackrel{0}{\wedge} \stackrel{1}{L}$	$\nu_\mu \stackrel{0}{\wedge} \stackrel{1}{R}$	
239	61	184	24	234	72	195	19	238
$\overline{e} \stackrel{+}{\wedge} \stackrel{1}{L}$	$\nu_\mu \stackrel{0}{\vee} \stackrel{1}{R}$	$\overline{e_T \phi} \stackrel{0 \rightarrow 1}{\wedge} \stackrel{1}{L}$	$\nu_\tau \stackrel{0}{\vee} \stackrel{1}{R}$	$\overline{e} \stackrel{+}{\wedge} \stackrel{1}{R}$	$\nu_\mu \stackrel{0}{\vee} \stackrel{1}{L}$	$\overline{e_S \phi} \stackrel{0 \rightarrow 1}{\wedge} \stackrel{1}{R}$	$\nu_\tau \stackrel{0}{\vee} \stackrel{1}{L}$	$\overline{e_S \phi} \stackrel{0 \rightarrow 1}{\wedge} \stackrel{1}{R}$
242	36	167	46	211	90	221	15	
$b \stackrel{-}{\vee} \stackrel{-1/3}{L}$	$u \stackrel{0}{\wedge} \stackrel{2/3}{R}$	$g^{gb} \stackrel{0}{\vee} \stackrel{1}{R}$	$\overline{c} \stackrel{0}{\wedge} \stackrel{1/3}{L}$	$c \stackrel{0}{\wedge} \stackrel{-1/3}{L}$	$\overline{g^{gb}} \stackrel{0}{\vee} \stackrel{1}{R}$	$\overline{u} \stackrel{0 \rightarrow -2/3}{\wedge} \stackrel{1}{R}$	$\overline{b} \stackrel{+}{\vee} \stackrel{1/3}{L}$	
47	35	241	45	166	164	37	14	243
$\overline{c} \stackrel{0}{\wedge} \stackrel{1/3}{L}$	$u \stackrel{2/3}{\wedge} \stackrel{1}{R}$	$b \stackrel{-1/3}{\vee} \stackrel{1}{L}$	$\overline{c} \stackrel{-2/3 \rightarrow 1/3}{\wedge} \stackrel{1}{L}$	$g^{rb} \stackrel{0}{\vee} \stackrel{1}{R}$	$\overline{g^{rb}} \stackrel{0}{\wedge} \stackrel{1}{R}$	$u \stackrel{0 \rightarrow 2/3}{\wedge} \stackrel{1}{R}$	$\overline{b} \stackrel{+}{\vee} \stackrel{1/3}{L}$	$b \stackrel{-}{\vee} \stackrel{-1/3}{L}$
220	93	212	16	222	210			
$\overline{c} \stackrel{0}{\wedge} \stackrel{1/3}{L}$	$u \stackrel{2/3}{\wedge} \stackrel{1}{R}$	$b \stackrel{-1/3}{\vee} \stackrel{1}{L}$	$\overline{c} \stackrel{-2/3 \rightarrow 1/3}{\wedge} \stackrel{1}{L}$	$g^{rb} \stackrel{0}{\vee} \stackrel{1}{R}$	$\overline{g^{rb}} \stackrel{0}{\wedge} \stackrel{1}{R}$	$u \stackrel{0 \rightarrow 2/3}{\wedge} \stackrel{1}{R}$	$\overline{b} \stackrel{+}{\vee} \stackrel{1/3}{L}$	$\overline{u} \stackrel{0 \rightarrow -2/3}{\wedge} \stackrel{1}{R}$

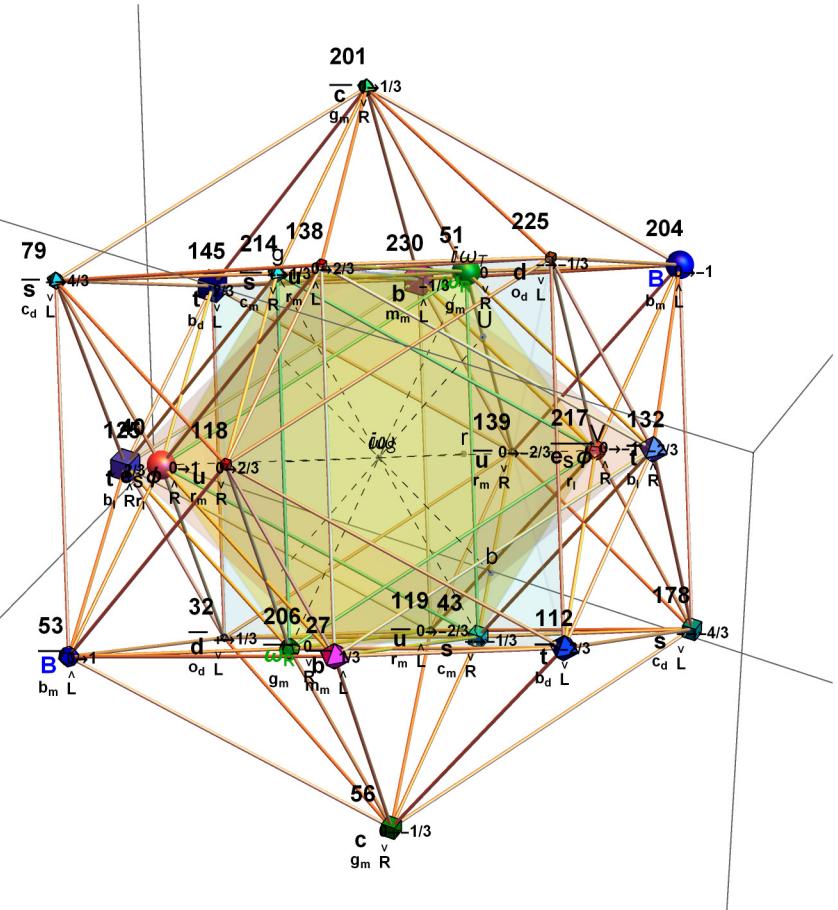
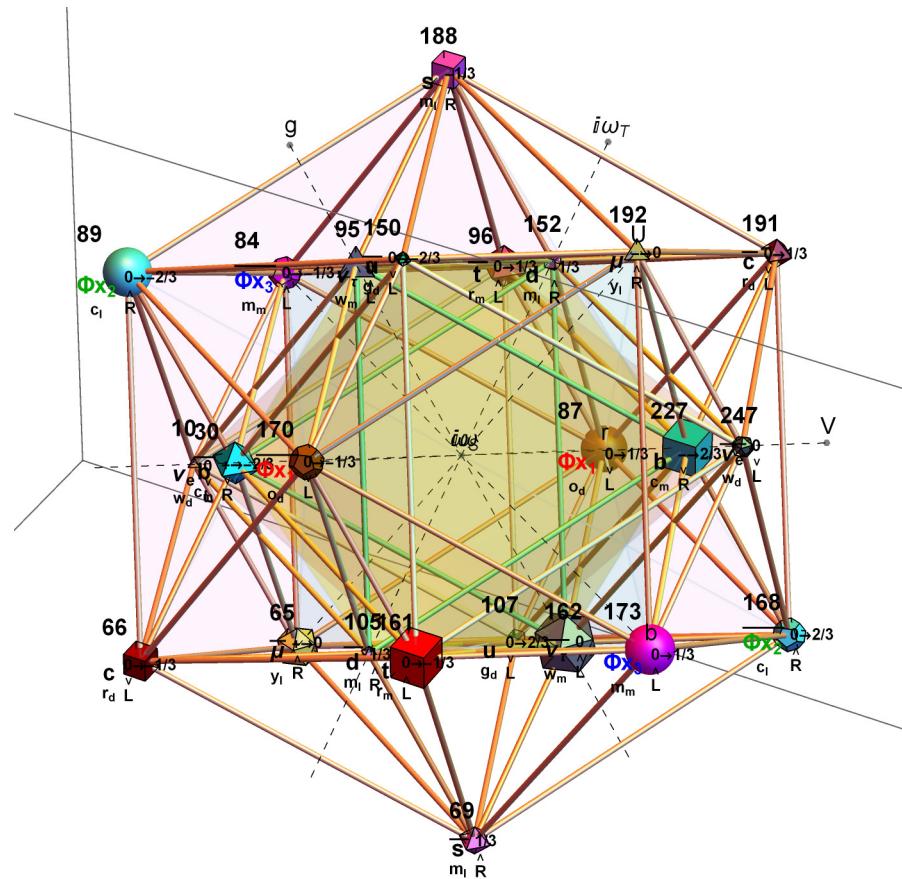
H4 (left) and H4Φ (right) Snub 24-Cell (3rd of 4 rotations by  $\frac{\pi}{5}$ )



```
ColumnForm[MatrixForm[{Row@{Column[{#, pDisp@#, pLabel@#, Center}] & /@ #}]} & /@ {h4snub163, h4snub83, h4@snub163, h4@snub83}]
```



H4 (left) and H4Φ (right) Snub 24-Cell (4th of 4 rotations by  $\frac{\pi}{5}$ )



```
ColumnForm[MatrixForm[{Row@{Column[{#, pDispem, pLbem}, Center]} & /@ #]} & /@ {h4snub164, h4snub84, h4snub164, h4snub84}]
```

227	188	247	87	170	10	69	30	
$b_v \xrightarrow{v} -2/3$ $c_m R$	$s_v \xrightarrow{v} -1/3$ $m_l R$	$\overline{v}_e \xrightarrow{v} 0$ $w_d L$	$\Phi x_1 \xrightarrow{v} 0 \rightarrow 1/3$ $o_d L$	$\Phi \overline{x}_1 \xrightarrow{v} 0 \rightarrow -1/3$ $o_d L$	$v_e \xrightarrow{v} 0$ $w_d L$	$\overline{s}_m \xrightarrow{v} 1/3$ $m_l R$	$\overline{b}_v \xrightarrow{v} +\rightarrow -2/3$ $c_m R$	
66	65	161	162	89	84	150	152	
$c_v \xrightarrow{v} 0 \rightarrow -1/3$ $r_d L$	$\overline{\mu} \xrightarrow{v} +\rightarrow 0$ $y_l R$	$t \xrightarrow{v} 0 \rightarrow -1/3$ $r_m L$	$\overline{v}_\tau \xrightarrow{v} 0$ $w_m L$	$\Phi x_2 \xrightarrow{v} 0 \rightarrow -2/3$ $c_l R$	$\Phi \overline{x}_3 \xrightarrow{v} 0 \rightarrow -1/3$ $m_m L$	$\overline{u} \xrightarrow{v} 0 \rightarrow -2/3$ $g_d L$	$d \xrightarrow{v} -1/3$ $m_l R$	$\overline{d} \xrightarrow{v} 1/3$ $m_l R$
217	139	201	132	125	56	118	40	
$\overline{e}_S \phi \xrightarrow{v} 0 \rightarrow -1$ $r_i R$	$\overline{u} \xrightarrow{v} 0 \rightarrow -2/3$ $r_m R$	$\overline{c} \xrightarrow{v} 0 \rightarrow 1/3$ $g_m R$	$\overline{t} \xrightarrow{v} -2/3$ $b_l R$	$t \xrightarrow{v} 2/3$ $b_l R$	$c \xrightarrow{v} 0 \rightarrow -1/3$ $g_m R$	$u \xrightarrow{v} 0 \rightarrow 2/3$ $r_m R$	$e_S \phi \xrightarrow{v} 0 \rightarrow 1$ $r_i R$	
204	51	225	178	230	138	43	145	
$B \xrightarrow{v} 0 \rightarrow -1$ $b_m L$	$\omega_R \xrightarrow{v} 0$ $g_m R$	$d \xrightarrow{v} -\rightarrow -1/3$ $o_d L$	$s \xrightarrow{v} -\rightarrow -4/3$ $c_d L$	$b \xrightarrow{v} -1/3$ $m_m L$	$u \xrightarrow{v} 0 \rightarrow 2/3$ $r_m L$	$s \xrightarrow{v} -\rightarrow -1/3$ $c_m R$	$t \xrightarrow{v} 2/3$ $b_d L$	$\overline{t} \xrightarrow{v} -2/3$ $b_d L$
$\overline{s} \xrightarrow{v} +\rightarrow 1/3$ $c_m R$	$\overline{u} \xrightarrow{v} 0 \rightarrow -2/3$ $r_m L$	$\overline{b} \xrightarrow{v} 1/3$ $m_m L$	$\overline{s} \xrightarrow{v} +\rightarrow 4/3$ $c_d L$	$\overline{d} \xrightarrow{v} +\rightarrow 1/3$ $o_d L$	$\overline{\omega}_R \xrightarrow{v} 0$ $g_m R$	$\overline{B} \xrightarrow{v} 0 \rightarrow 1$ $b_m L$		