

### Three historical (reverse order) forms of the E8 ↔ H<sub>8</sub> folding matrix :

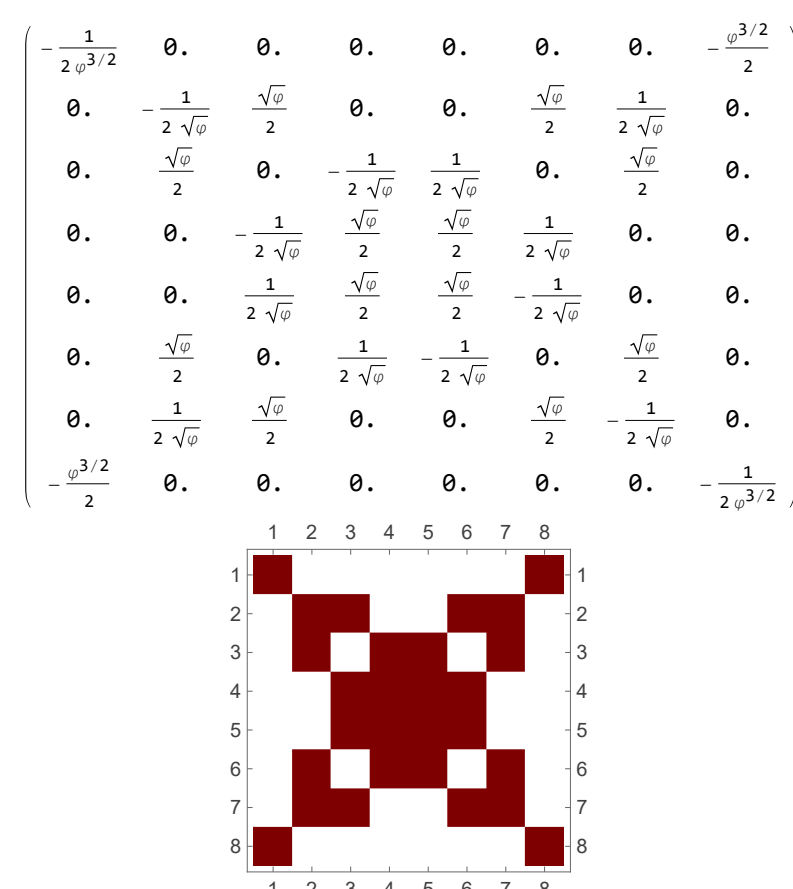
The current centrosymmetric, traceless (Tr=0), and volume preserving (Det=1) form with features analyzed in:

- The\_Isomorphism\_of\_H4\_and\_E8 <https://arxiv.org/abs/2311.01486>
- The\_Isomorphism\_of\_3-Qubit\_Hadamards\_and\_E8 <https://arxiv.org/abs/2311.11918>

It transforms a (Left 4D) H<sub>4</sub> (the 120 vertex 600-cell) into a second scaled (palindromically reversed Right 4D) φH<sub>4</sub> copy with a Galois transform φ ↔ 1/φ.

Those L+R (now 8D) are palindromically reversed and combined into 240 vertices by H<sub>2</sub><sup>2</sup>=H<sub>4L+R</sub>+φH<sub>4L+R</sub> that give you back E<sub>8</sub> upon rotation (folding/unfolding) by U<sup>-1</sup>.

```
In[ ]:= matCheck@octSym@DetIU // MatrixForm
Out[ ]://MatrixForm=
```

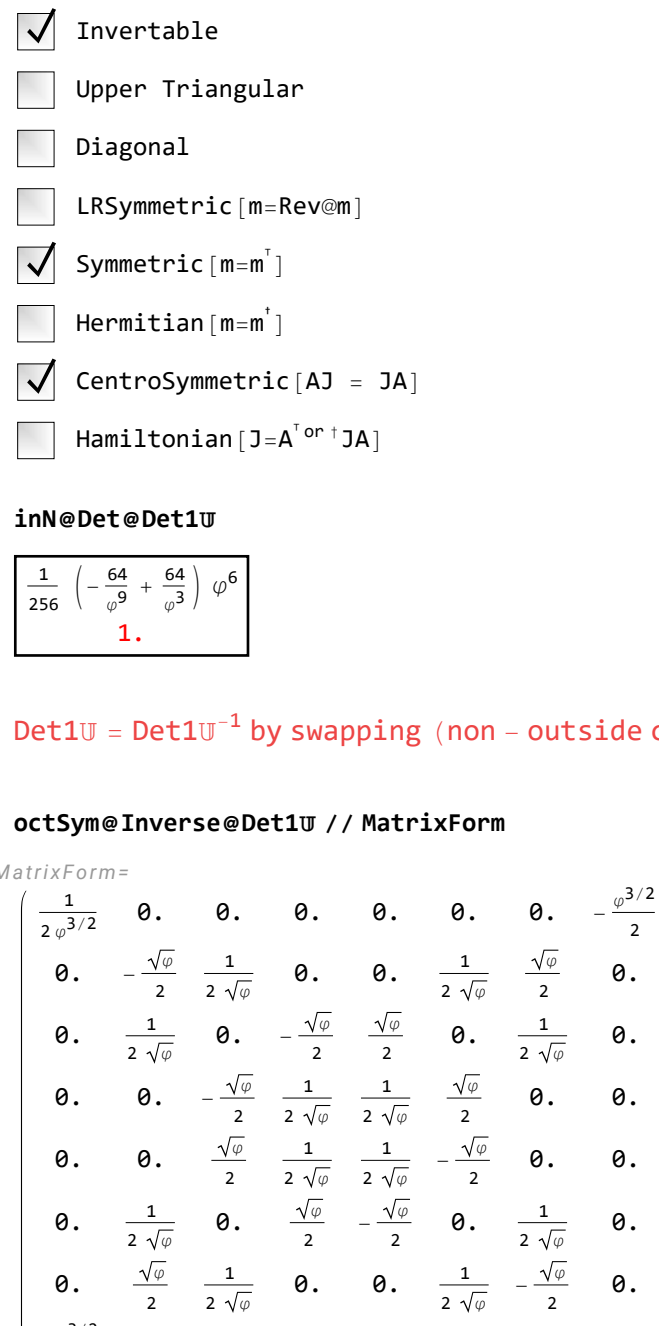


```
In[ ]:= in@Det@DetIU
```

Out[ ]:=  $\frac{1}{256} \left( \frac{64}{\sqrt{\varphi}} + \frac{64}{\sqrt{\varphi^3}} \right) \varphi^6$

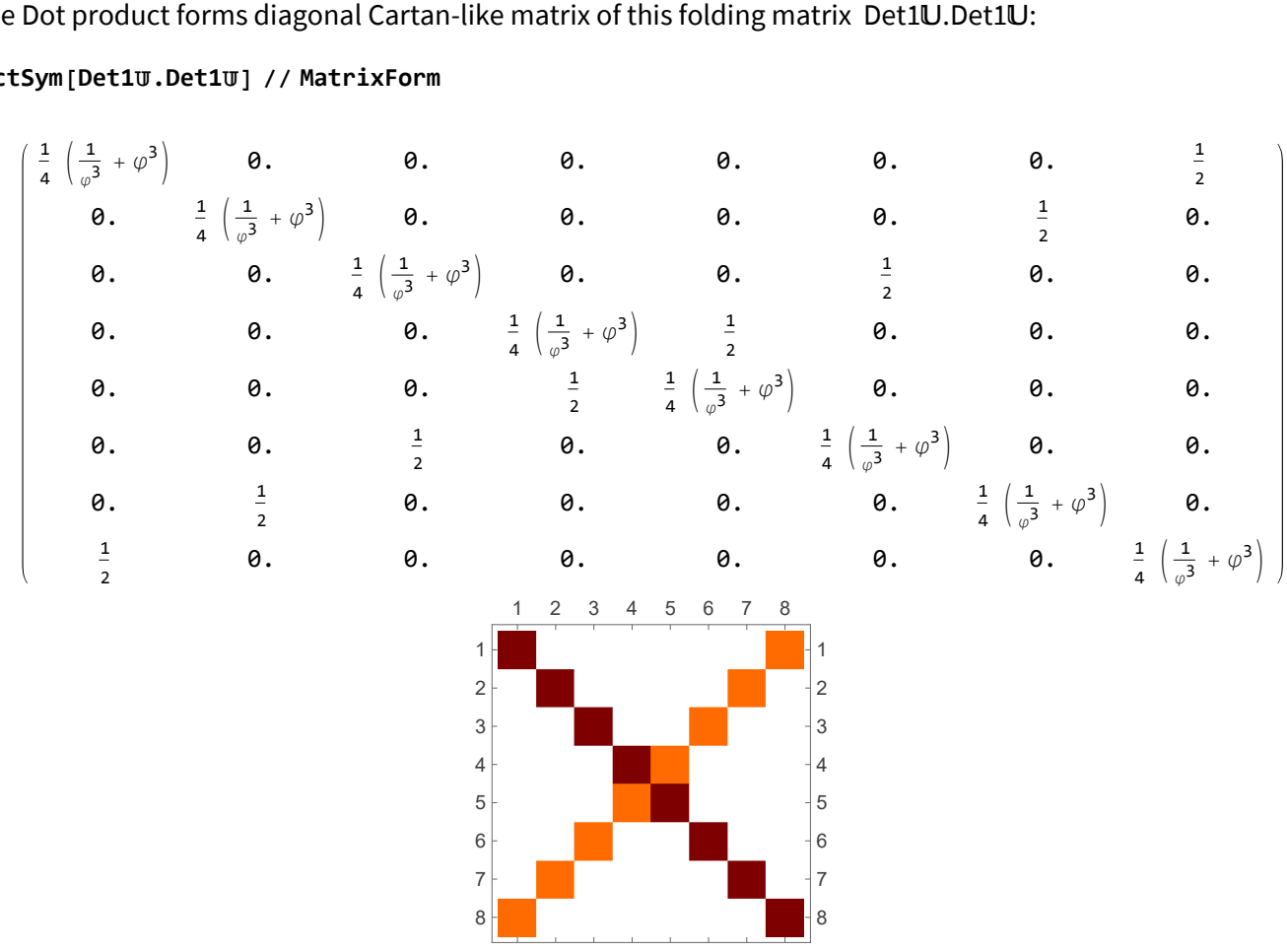
DetIU = DetIU<sup>-1</sup> by swapping (non - outside corner)  $\sqrt{\varphi} \leftrightarrow \frac{1}{\sqrt{\varphi}}$

```
In[ ]:= octSym@Inverse@DetIU // MatrixForm
Out[ ]://MatrixForm=
```



DetIU<sup>2</sup> as the Dot product forms diagonal Cartan-like matrix of this folding matrix DetIU.DetIU:

```
In[ ]:= matCheck@octSym[DetIU.DetIU] // MatrixForm
Out[ ]://MatrixForm=
```



An older (but easier to read symbolically) Det=1 form:

This is just an unscaled version of the current DetIU...

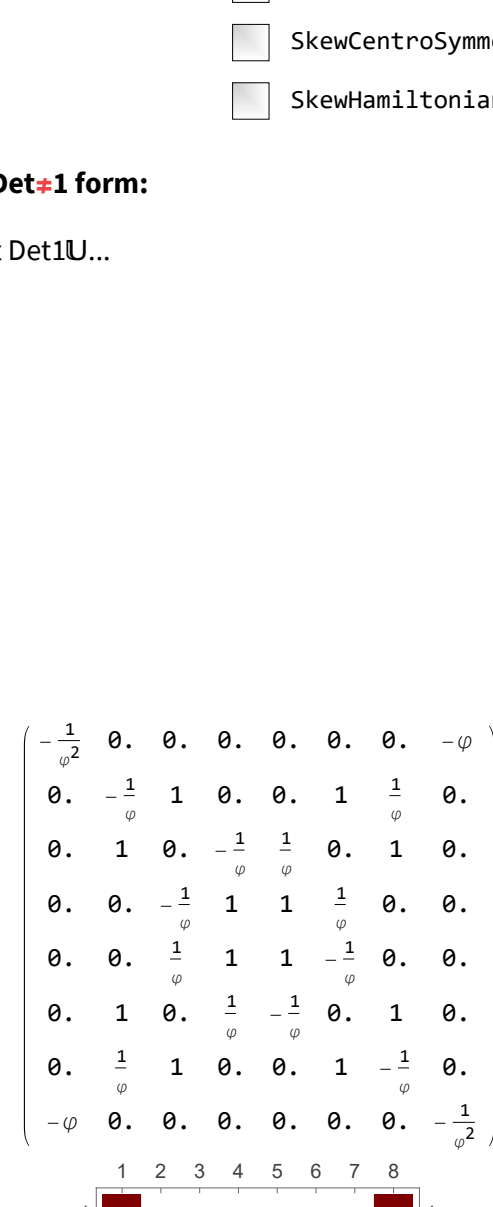
```
In[ ]:= U@Det1f
```

DetIU = U / % // MatrixForm

Out[ ]:=  $2 \sqrt{\frac{1}{\varphi}}$

```
Out[ ]://MatrixForm= True
```

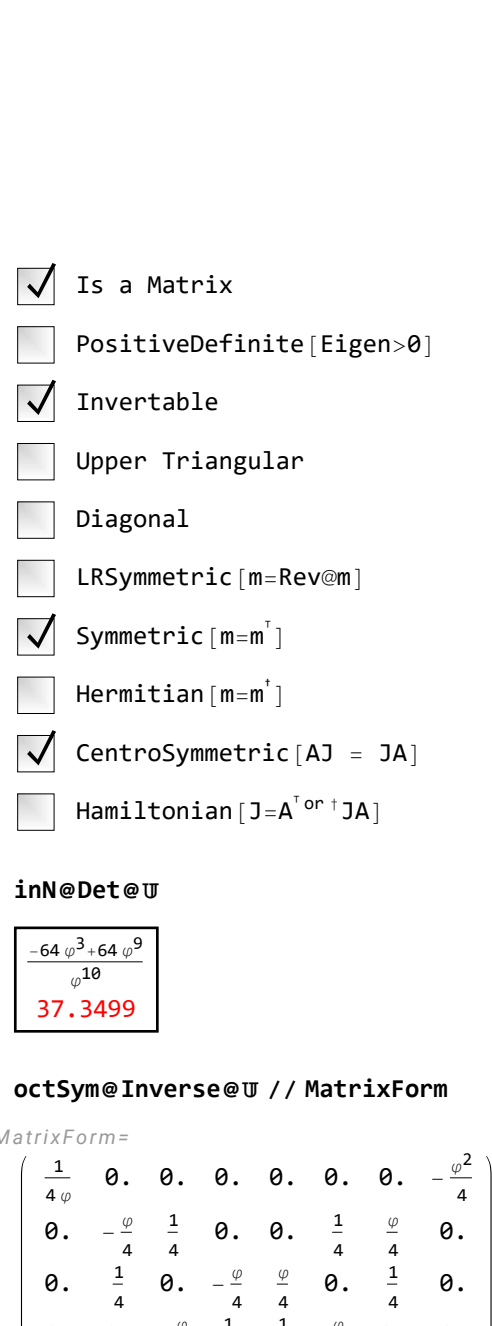
```
In[ ]:= matCheck@octSym@U // MatrixForm
Out[ ]://MatrixForm=
```



```
In[ ]:= in@Det@U
```

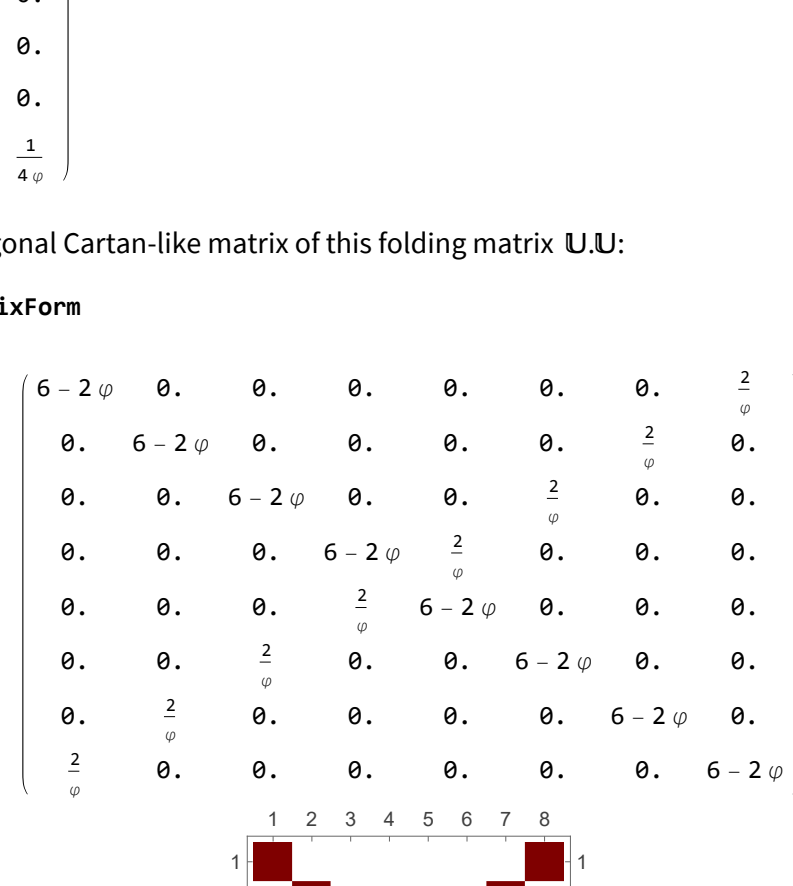
Out[ ]:=  $\frac{-64\sqrt{3}\sqrt{64}\sqrt{\varphi}}{25}$

```
In[ ]:= octSym@Inverse@U // MatrixForm
Out[ ]://MatrixForm=
```



U<sup>2</sup> as the Dot product forms diagonal Cartan-like matrix of this folding matrix U.U:

```
In[ ]:= matCheck@octSym[U.U] // MatrixForm
Out[ ]://MatrixForm=
```

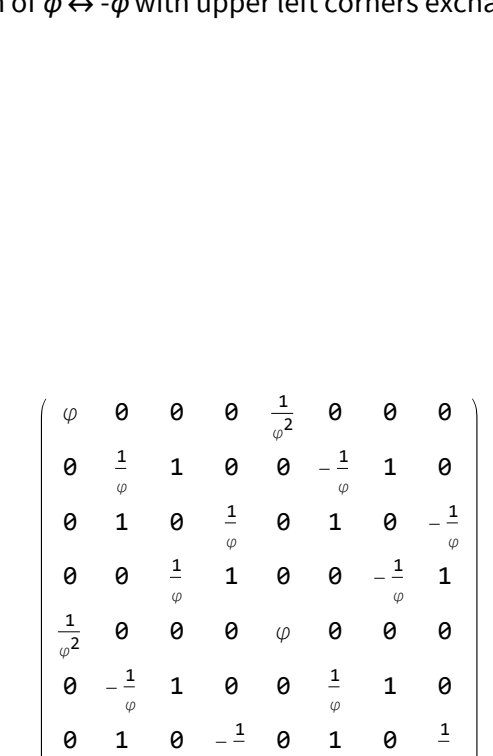


The original 2012-2014 L/R quadrant preserving as an E<sub>8</sub> to canonical 600-cell (H<sub>4</sub> family of polytopes) form :

Where L/R quadrants have a Galois transform of φ ↔ -φ with upper left corners exchanging φ ↔ φ<sup>2</sup>:

In[ ]:= H4fold =  $\begin{pmatrix} \varphi & 0 & 0 & 0 & \varphi^2 & 0 & 0 & 0 \\ 0 & \varphi & 1 & 0 & 0 & -\varphi & 1 & 0 \\ 0 & 1 & 0 & \varphi & 1 & 0 & 0 & -\varphi \\ 0 & 0 & \varphi & 1 & 0 & 0 & -\varphi & 1 \\ \varphi^2 & 0 & 0 & 0 & \varphi & 0 & 0 & 0 \\ 0 & -\varphi & 1 & 0 & 0 & \varphi & 1 & 0 \\ 0 & 0 & 1 & 0 & -\varphi & 0 & 1 & 0 \\ 0 & 0 & -\varphi & 1 & 0 & 0 & \varphi & 1 \end{pmatrix}$ ;

```
In[ ]:= matCheck@H4fold
```

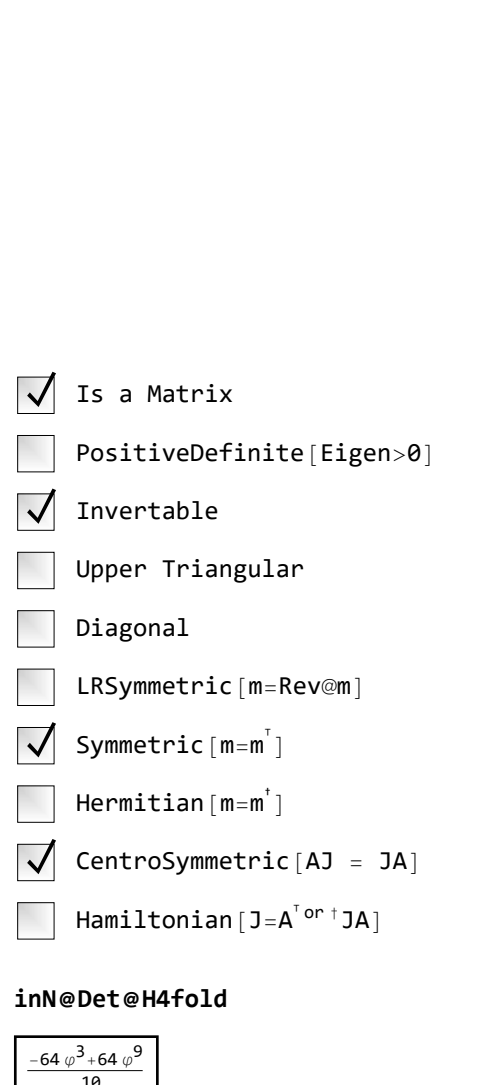


```
Out[ ]:=
```

```
In[ ]:= in@Det@H4fold
```

Out[ ]:=  $\frac{-64\sqrt{3}\sqrt{64}\sqrt{\varphi}}{25}$

```
In[ ]:= octSym@Inverse@H4fold // MatrixForm
Out[ ]://MatrixForm=
```



H4fold<sup>2</sup> as the Dot product forms diagonal Cartan-like matrix of this folding matrix H4fold.H4fold:

```
In[ ]:= matCheck@octSym[H4fold.H4fold] // MatrixForm
Out[ ]://MatrixForm=
```

